NEWTON'S LAWS OF MOTION

FORCE 1.

LLI

A pull or push which changes or tends to change the state of rest or of uniform motion or direction of motion of any object is called force. Force is the interaction between the object and the source (providing the pull or push). It is a vector quantity.

Effect of resultant force :

- (1) may change only speed
- (2) may change only direction of motion.
- (3) may change both the speed and direction of motion.
- (4) may change size and shape of a body

Unit of force : Newton and $\frac{\text{kg} \cdot \text{m}}{\text{s}^2}$ (MKS System)

dyne and $\frac{g \cdot cm}{s^2}$ (CGS System)

1 Newton = 10^5 dyne

Kilogram force (kgf): The force with which earth attracts a 1kg body towards its centre is called kilogram force, thus

kgf = Forece in newton g

Dimensional Formula of force : [MLT⁻²]

1.1 **Fundamental Forces**

All the forces observed in nature such as muscular force, tension, reaction, friction, elastic, weight, electric, magnetic, nuclear, etc., can be explained in terms of only following four basic interactions:

(A) Gravitational Force : The force of interaction which exists between two particles of masses m1 and m₂, due to their masses is called gravitational force.

$$\vec{F} = -G \frac{m_1 m_2}{r^3} \vec{r}$$
 $S \stackrel{\vec{r}}{\longrightarrow} T$

= position vector of test particle 'T' with respect to source particle 'S'. and G = universal gravitational constant $= 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2$.

(i) It is the weakest force and is always attractive.

(ii) It is a long range force as it acts between any two particles situated at any distance in the universe.

(iii) It is independent of the nature of medium between the particles.

An apple is freely falling as shown in figure, When it is at a

height h, force between earth and apple is given by

$$\mathsf{F} = \frac{\mathsf{GM}_{e}\mathsf{m}}{(\mathsf{R}_{e} + \mathsf{h})^{2}}$$

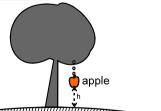
apple

mmmmmmm Earth

where M_e – mass of earth, R_e – radius of earth. It acts towards earth's centre. Now rearranging above result.

$$\mathsf{F} = \mathsf{m} \frac{\mathsf{GM}_{\mathsf{e}}}{\mathsf{R}_{\mathsf{e}}^{\ 2}} \ . \left(\frac{\mathsf{R}_{\mathsf{e}}}{\mathsf{R}_{\mathsf{e}} + \mathsf{h}}\right)^{2}.$$

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$$F = mg \left(\frac{R_{e}}{R_{e} + h}\right)^{2} \left\{g = \frac{GM_{e}}{R_{e}^{2}}\right\}$$

Here h << R_e, so $\frac{R_{e}}{R_{e} + h} \approx 1$...

Here h << R_e, so

∴ F = mg

This is the force exerted by earth on any particle of mass m near the earth surface. The value of g = 9.81 m/s² \approx 10 m/s² π^2 m/s² \approx 32 ft/s². It is also called acceleration due to gravity near the surface of earth.

(B) Electromagnetic Force : Force exerted by one particle on the other because of the electric charge on the particles is called electromagnetic force.

Following are the main characteristics of electromagnetic force

- (a) These can be attractive or repulsive.
- (b) These are long range forces
- (c) These depend on the nature of medium between the charged particles.
- (d) All macroscopic forces (except gravitational) which we experience as push or pull or by contact are electromagnetic, i.e., tension in a rope, the force of friction, normal reaction, muscular force, and force experienced by a deformed spring are electromagnetic forces. These are manifestations of the electromagnetic attractions and repulsions between atoms/molecules.
- (C) Nuclear Force : It is the strongest force. It keeps nucleons (neutrons and protons) together inside the nucleus inspite of large electric repulsion between protons. Radioactivity, fission, and fusion, etc. result because of unbalancing of nuclear forces. It acts within the nucleus that too upto a very small distance.
- (D) Weak Force : It acts between any two elementary particles. Under its action a neutron can change into a proton emitting an electron and a particle called antineutrino. The range of weak force is very small, in fact much smaller than the size of a proton or a neutron. It has been found that for two protons at a distance of 1 Fermi : FN: FEM: FW: FG:: 1: 10⁻²: 10⁻⁷: 10⁻³⁸

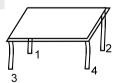
1.2 Classification of forces on the basis of contact :

- (A) Field Force : Force which acts on an object at a distance by the interaction of the object with the field produced by other object is called field force. Examples
 - (a) Gravitation force (b) Electromagnetic force
- (B) Contact Force : Forces which are transmitted between bodies by short range atomic molecular interactions are called contact forces. When two objects come in contact they exert contact forces on each other.

Examples :

(a) Normal force (N) :

It is the component of contact force perpendicular to the surface. It measures how strongly the surfaces in contact are pressed against each other. It is the electromagnetic force. A table is placed on Earth as shown in figure



Here table presses the earth so normal force exerted by four legs of table on earth are as shown in figure.

$$\downarrow$$
 N₁ \downarrow N₂ ground

Now a boy pushes a block kept on a frictionless surface.

Block

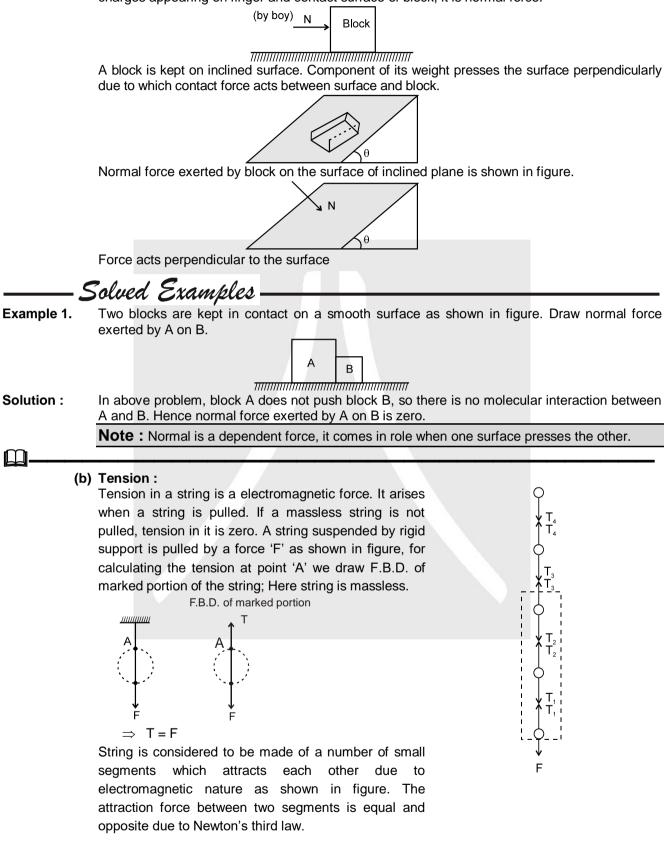


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Here, force exerted by boy on block is electromagnetic interaction which arises due to similar charges appearing on finger and contact surface of block, it is normal force.



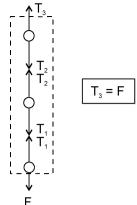
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For calculating tension at any segment, we consider two or more than two parts as a system.



Here interaction between segments are considered as internal forces, so they are not shown in F.B.D.

(C) Frictional force : It is the component of contact force tangential to the surface. It opposes the relative motion (or attempted relative motion) of the two surfaces in contact.

2. THIRD LAW OF MOTION :

To every action, there is always an equal and opposite reaction. Newton's law from an 1803 translation from Latin as Newton wrote

"To every action there is always opposed an equal and opposite reaction : to the mutual actions of two bodies upon each other are always equal, and directed to contrary parts."

2.1 Important points about the Third Law

- (a) The terms 'action' and 'reaction' in the Third Law mean nothing else but 'force'. A simple and clear way of stating the Third Law is as follows : Forces always occur in pairs. Force on a body A by B is equal and opposite to the force on the body B by A.
- (b) The terms 'action' and 'reaction' in the Third Law may give a wrong impression that action comes before reaction i.e. action is the cause and reaction the effect. There is no such cause-effect relation implied in the Third Law. The force on A by B and the force on B by A act at the same instant. Any one of them may be called action and the other reaction.
- (c) Action and reaction forces act on different bodies, not on the same body. Thus if we are considering the motion of any one body (A or B), only one of the two forces is relevant. It is an error to add up the two forces and claim that the net force is zero.

However, if you are considering the system of two bodies as a whole, F_{AB} (force on A due to B) and F_{BA} (force on B due to A) are internal forces of the system (A + B). They add up to give a null force. Internal forces in a body or a system of particles thus cancel away in pairs. This is an important fact that enables the Second Law to be applicable to a body or a system of particles.

3. SYSTEM :

Two or more than two objects which interact with each other form a system.

- 3.1 Classification of forces on the basis of boundary of system :
 - (A) Internal Forces : Forces acting each with in a system among its constituents.
 - **(B)** External Forces : Forces exerted on the constituents of a system by the outside surroundings are called as external forces.
 - (C) Real Force : Force which acts on an object due to other object is called as real force. An isolated object (far away from all objects) does not experience any real force.



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4. FREE BODY DIAGRAM

A free body diagram consists of a diagrammatic representations of a single body or a subsystem of bodies isolated from its surroundings showing all the forces acting on it.

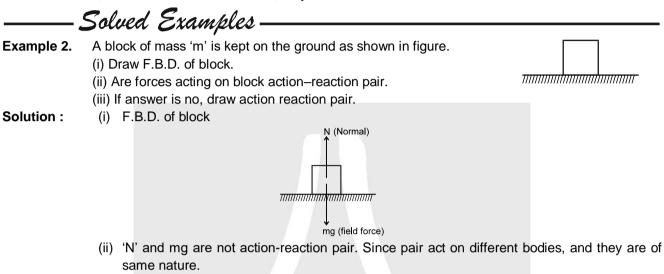
4.1 Steps for F.B.D.

Step 1 : Identify the object or system and isolate it from other objects clearly specifying its boundary.

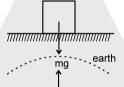
Step 2 : First draw non-contact external force in the diagram. Generally it is weight.

Step 3 : Draw contact forces which acts at the boundary of the object or system. Contact forces are normal, friction, tension and applied force.

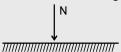
In F.B.D, internal forces are not drawn, only external are drawn.



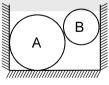
(iii) Pair of 'mg' of block acts on earth in opposite direction.



and pair of 'N' acts on surface as shown in figure.



Example 3. Two sphere A and B are placed between two vertical walls as shown in figure. Draw the free body diagrams of both the spheres.



Solution : F.B.D. of sphere 'A' :





F.B.D. of sphere 'B' : (exerted by A) **Note :** Here N_{AB} and N_{BA} are the action–reaction pair (Newton's third law).

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5. NEWTON'S LAWS OF MOTION :

5.1 First Law of Motion

Each body continues to be in its state of rest or of uniform motion in a straight line unless compelled by some external force to act otherwise.

Newton's first law is really a statement about reference frames in that it defines the types of reference frames in which the laws of Newtonian mechanics hold. From this point of view the first law is expressed as:

If the net force acting on a body is zero, it is possible to find a set of reference frames in which that body has no acceleration.

Newton's first law is sometimes called the law of inertia and the reference frames that it defines are called inertial reference frames.

Newton's law from an 1803 translation from Latin as Newton wrote

"Every body preserves in its state of rest, or of uniform motion in a right line, unless it is compelled to change that state by forces impressed thereon."

Examples of this law :

- (a) A bullet fired on a glass window makes a clean hole through it while a stone breaks the whole of it. The speed of bullet is very high. Due to its large inertia of motion, it cuts a clean hole through the glass. When a stone is thrown, it inertia is much lower so it cannot cut through the glass.
- (b) A passenger sitting in a bus gets a jerk when the bus starts or stops suddenly.

5.2 Second Law of Motion :

The rate of change of momentum of a body is proportional to the applied force and takes place in the direction in which the force acts.

Newton's law from an 1803 translation from Latin as Newton wrote

"The alteration of motion is ever proportional to the motive force impressed; and is made in the direction of the right line in which that force is impressed."

Mathematically

$$\vec{F} = \frac{d\vec{p}}{dt}$$

Or $\vec{F} = m\vec{a}$

where $\vec{p} = m\vec{v}$, \vec{p} = Linear momentum.

In case of two particles having linear momentum \vec{P}_1 and \vec{P}_2 and moving towards each other under mutual forces, from Newton's second law;

$$\frac{d}{dt}\left(\vec{p}_{1}+\vec{p}_{2}\right) = \vec{F} = 0 \implies \frac{d\vec{p}_{1}}{dt} + \frac{d\vec{p}_{2}}{dt} = 0$$

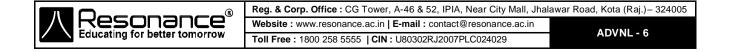
 $\vec{F}_1 + \vec{F}_2 = 0 \qquad \Rightarrow \quad \vec{F}_2 = -\vec{F}_1$ which is Newton's third law.

5.3 Important points about second law

- (a) The Second Law is obviously consistent with the First Law as F = 0 Implies a = 0.
- (b) The Second Law of motion is a vector law. It is actually a combination of three equations, one for each component of the vectors :

$$F_x = \frac{dp_x}{dt} = ma_x$$
 $F_y = \frac{dp_y}{dt} = ma_y$ $F_z = \frac{dp_z}{dt} = ma_z$

This means that if a force is not parallel to the velocity of the body, but makes some angle with it, it changes only the component of velocity along the direction of force. The component of velocity normal to the force remains unchanged.







- (c) The Second Law of motion given above is strictly applicable to a single point mass. The force F in the law stand for the net external force on the particle and a stands for the acceleration of the particle. Any internal forces in the system are not to be included in F.
- (d) The Second Law of motion is a local relation. What this means is that the force F at a point in space (location of the particle) at a certain instant of time is related to a at the same point at the same instant. That is acceleration here and now is determined by the force here and now not by any history of the motion of the particle.

5.4 **Applications of Newton's Laws**

(a) When objects are in equilibrium

To solve problems involving objects in equilibrium:

Step 1 : Make a sketch of the problem.

Step 2 : Isolate a single object and then draw the free-body diagram for the object. Label all external forces acting on it.

Step 3 : Choose a convenient coordinate system and resolve all forces into rectangular components along x and y direction.

Step 4: Apply the equations $\Sigma F_x = 0$ and $\Sigma F_y = 0$.

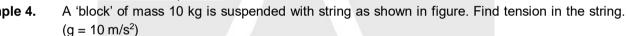
Step 5: Step 4 will give you two equations with several unknown quantities. If you have only two unknown quantities at this point, you can solve the two equations for those unknown quantities.

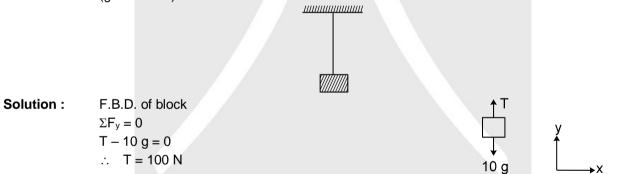
Step 6: If step 5 produces two equations with more than two unknowns, go back to step 2 and select another object and repeat these steps.

Eventually at step 5 you will have enough equations to solve for all unknown quantities.

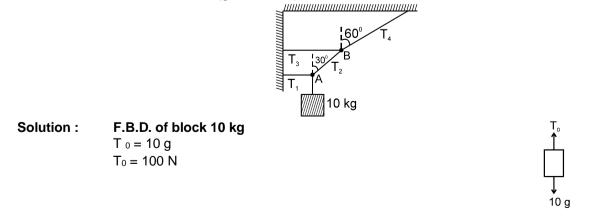


Example 4.

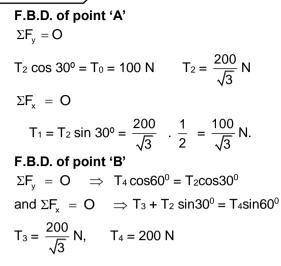


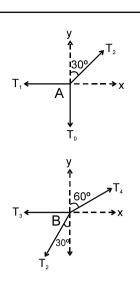


Example 5. The system shown in figure is in equilibrium. Find the magnitude of tension in each string; $T_1, T_2, T_3 \text{ and } T_4. (g = 10 \text{ m/s}^{-2})$

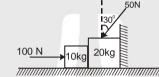


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Example 6. Two blocks are kept in contact as shown in figure. Find



- (a) forces exerted by surfaces (floor and wall) on blocks.
- (b) contact force between two blocks.

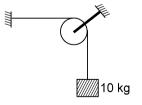
Solution : F.B.D. of 10 kg block

$$\begin{array}{c} 100 \text{ N} \\ \xrightarrow{} \\ 10 \text{ g} \end{array}$$

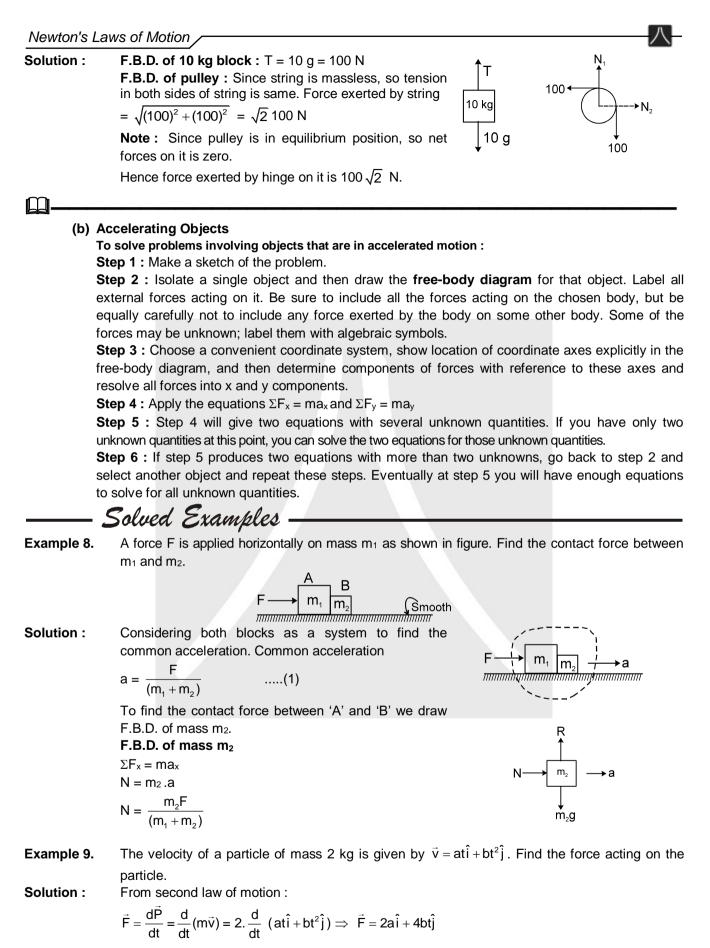
$$\begin{split} N_1 &= 10 \text{ g} = 100 \text{ N} & \dots..(1) \\ N_2 &= 100 \text{ N} & \dots..(2) \\ \textbf{F.B.D. of 20 kg block} \\ N_2 &= 50 \sin 30^\circ + N_3 \\ \therefore \quad N_3 &= 100 - 25 = 75 \text{ N} & \dots..(3) \\ and N_4 &= 50 \cos 30^\circ + 20 \text{ g} \\ N_4 &= 243.30 \text{ N} \end{split}$$

 $N_2 \longrightarrow D_2 \longrightarrow D_2$

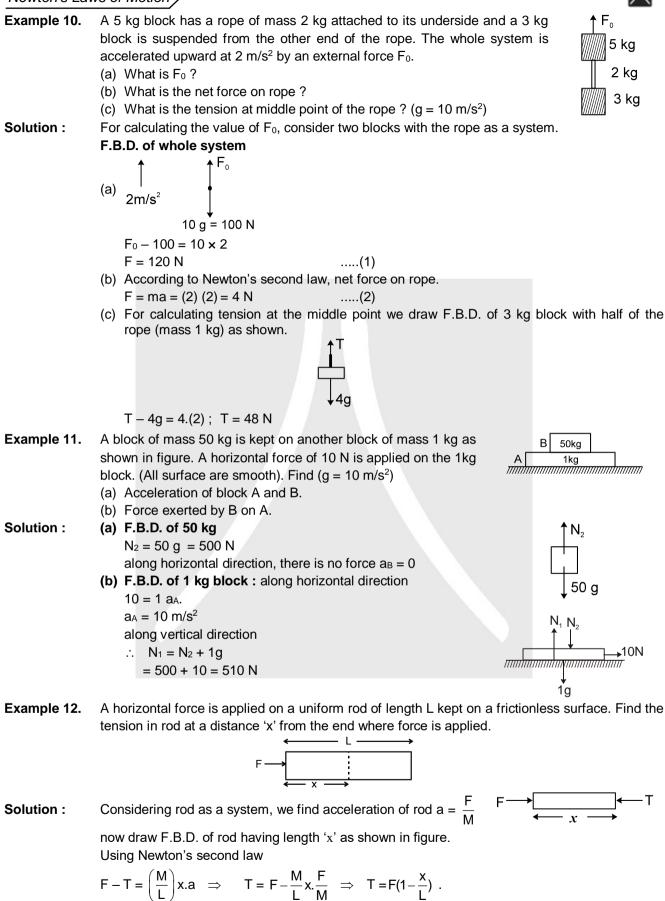
Example 7. Find magnitude of force exerted by string on pulley.

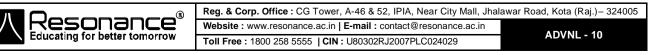


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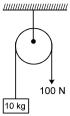




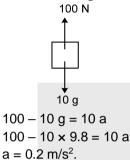




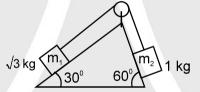
Example 13. One end of string which passes through pulley and connected to 10 kg mass at other end is pulled by 100 N force. Find out the acceleration of 10 kg mass. ($g = 9.8 \text{ m/s}^2$)



Solution :Since string is pulled by 100 N force. So tension in the string is 100 N.F.B.D. of 10 kg block



Example 14. Two blocks m₁ and m₂ are placed on a smooth inclined plane as shown in figure. If they are released from rest. Find :



(i) Acceleration of mass m_1 and m_2

- (ii) Tension in the string
- (iii) Net force on pulley exerted by string

Solution :

$$\frac{\sqrt{3}}{2}$$
 g - T = $\sqrt{3}$ a(1)

F.B.D. of m₂ : $T - m_2gsin\theta = m_2a$

F.B.D. of m₁ : $m_1gsin\theta - T = m_1a$

T - 1.
$$\frac{\sqrt{3}}{2}$$
 g = 1.a(2)

Adding eq.(1) and (2) we get a = 0Putting this value in eq.(i) we get

$$T = \frac{\sqrt{3}g}{2},$$

F.B.D. of pulley

$$F_{\rm R} = \sqrt{2} T$$
$$F_{\rm R} = \sqrt{\frac{3}{2}} g$$

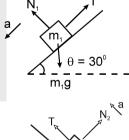
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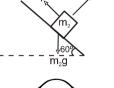
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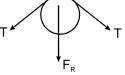
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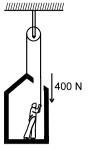








Example 15. A 60 kg painter stands on a 15 kg platform. A rope attached to the platform and passing over an overhead pulley allows the painter to raise himself along with the platform.



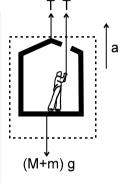
- (i) To get started, he pulls the rope down with a force of 400 N. Find the acceleration of the platform as well as that of the painter.
- (ii) What force must he exert on the rope so as to attain an upward speed of 1 m/s in 1s?
- (iii) What force should he apply now to maintain the constant speed of 1 m/s?

The free body diagram of the painter and the platform as a system can be drawn as shown in the figure. Note that the tension in the string is equal to the force by which he pulls the rope.

(i) Applying Newton's Second Law

$$2T - (M + m)g = (M + m)a$$

or $a = \frac{2T - (M + m)g}{M + m}$
Here M = 60 kg; m = 15 kg; T = 400 N
 $g = 10 \text{ m/s}^2$
 $a = \frac{2(400) - (60 + 15)(10)}{60 + 15} = 0.67 \text{ m/s}^2$



(ii) To attain a speed of 1 m/s in one second, the acceleration a must be 1 m/s². Thus, the applied force is

$$F = \frac{1}{2} (M + m) (g + a) = \frac{1}{2} (60 + 15) (10 + 1) = 412.5 N$$

(iii) When the painter and the platform move (upward) together with a constant speed, it is in a state of dynamic equilibrium.

Ν

Thus, 2F – (M + m) g = 0
or F =
$$\frac{(M+m)g}{(60+15)(10)} = 37$$

or
$$F = \frac{(M+m)g}{2} = \frac{(60+15)(10)}{2} = 375$$

\square

Solution :

6. **WEIGHING MACHINE:**

A weighing machine does not measure the weight but measures the force exerted by object on its upper surface.

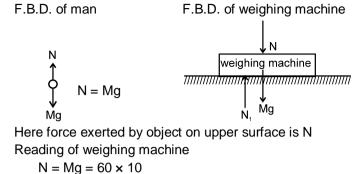
A man of mass 60 Kg is standing on a weighing machine placed on ground. Calculate the Example 16. reading of machine ($g = 10 \text{ m/s}^2$).





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Solution : For calculating the reading of weighing machine, we draw F.B.D. of man and machine separately.

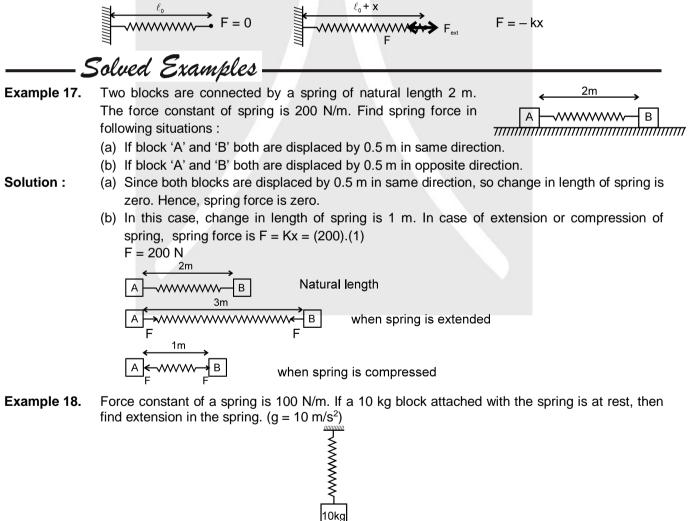


7. SPRING FORCE :

N = 600 N.

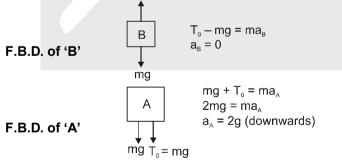
Every spring resists any attempt to change its length; when it is compressed or extended, it exerts force at its ends. The force exerted by a spring is given by F = -kx, where x is the change in length and k is the stiffness constant or spring constant (unit Nm⁻¹).

When spring is in its natural length, spring force is zero.





Solution : In this situation, spring is in extended state so spring force acts in upward direction. Let x be the extension in the spring. F.B.D. of 10 kg block : $F_s = 10g$ \Rightarrow Kx = 100 \Rightarrow (100)x = (100) 10a \Rightarrow x = 1m Example 19. Two blocks 'A' and 'B' of same mass 'm' attached with a light spring are suspended by a string as shown in figure. Find the acceleration of block 'A' and 'B' just after the string is cut. Am B m When block A and B are in equilibrium position Solution : \mathbf{I}_{0} В $T_0 = mg$ F.B.D of 'B'(1) mg F.B.D of 'A'(2) $T = mg + T_0$ A T = 2 mgmg T When string is cut, tension T becomes zero. But spring does not change its shape just after cutting. So spring force acts on mass B, again draw F.B.D. of blocks A and B as shown in figure $T_0 = mg$



m

7.1 **Spring Balance :**

It does not measure the weight. It measures the force exerted by the object at the hook.

Symbolically, it is represented as shown in figure. A block of mass 'm' is suspended at hook.

ŧ spring balance ~hook m



Newton's Laws of Motion

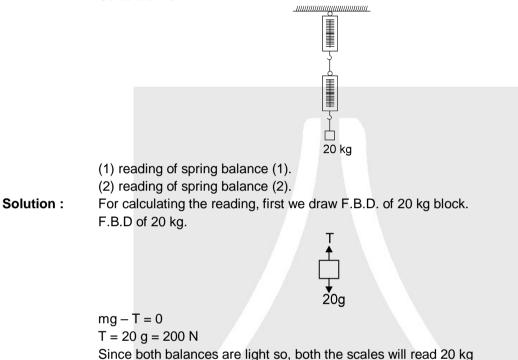
When spring balance is in equilibrium, we draw the F.B.D. of mass m for calculating the reading of balance.

F.B.D. of 'm'. mg - T = 0 T = mgMagnitude of T gives the reading of spring balance.

Example 20. A block of mass 20 kg is suspended through two light spring balances as shown in figure. Calculate the

m

ma



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8. CONSTRAINED MOTION:

8.1 String Constraint :

- When two objects are connected through a string and if the string have the following properties:
- (a) The length of the string remains constant i.e. inextensible string.
- (b) Always remains tight, does not slacks.

Then the parameters of the motion of the objects along the length of the string and in the direction of extension have a definite relation between them.

Steps for String Constraint

Step 1. Identify all the objects and number of strings in the problem.

Step 2. Assume variable to represent the parameters of motion such as displacement, velocity acceleration etc.

- (i) Object which moves along a line can be specified by one variable.
- (ii) Object moving in a plane are specified by two variables.
- (iii) Objects moving in 3-D requires three variables to represent the motion.

Step 3. Identify a single string and divide it into different linear sections and write in the equation format. $l_1 + l_2 + l_3 + l_4 + l_5 + l_6 = l$



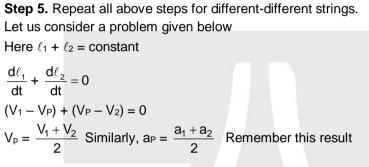
Step 4. Differentiate with respect to time

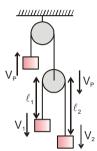
$$\frac{d\ell_1}{dt} + \frac{d\ell_2}{dt} + \frac{d\ell_3}{dt} + \dots = 0$$

 $\frac{d\ell_1}{dt}$ = represents the rate of increment of the portion 1, end points are always in contact with some

object so take the velocity of the object along the length of the string $\frac{d\ell_1}{dt} = V_1 + V_2$

Take positive sign if it tends to increase the length and negative sign if it tends to decrease the length. Here $+V_1$ represents that upper end is tending to increase the length at rate V_1 and lower end is tending to increase the length at rate V_2 .





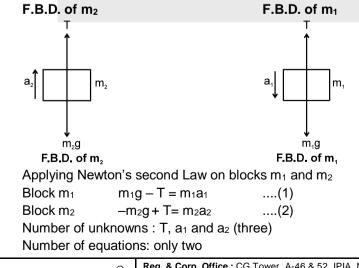
 m_2

Example 21. Two blocks of masses m_1 and m_2 are attached at the ends of an inextensible string which passes over a smooth massless pulley. If $m_1 > m_2$, find :

- (i) the acceleration of each block
- (ii) the tension in the string.
- **Solution :** The block m₁ is assumed to be moving downward and the block m₂ is assumed to be moving upward. It is merely an assumption and it does not imply the real direction.

does not imply the real direction. If the values of a_1 and a_2 come out to be positive then only the assumed directions are correct; otherwise the body moves in the opposite direction. Since the pulley is smooth and massless, therefore, the tension on each side of the pulley is same.

The free body diagram of each block is shown in the figure.





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Obviously, we require one more equation to solve the problem. Note that whenever one finds the number of equations less than the number of unknowns, one must think about the constraint relation. Now we are going to explain the mathematical procedure for this. How to determine Constraint Relation ?

- (1) Assume the direction of acceleration of each block, e.g. a_1 (downward) and a_2 (upward) in this case.
- (2) Locate the position of each block from a fixed point (depending on convenience), e.g. centre of the pulley in this case.
- (3) Identify the constraint and write down the equation of constraint in terms of the distance assumed. For example, in the chosen problem, the length of string remains constant is the constraint or restriction.

Thus, $x_1 + x_2 = constant$

Differentiating both the sides w.r.t. time we get $\frac{dx_1}{dt} + \frac{dx_2}{dt} = 0$

Each term on the left side represents the velocity of the blocks.

Since we have to find a relation between accelerations, therefore we differentiate it once again w.r.t. time.

Thus
$$\frac{d^2 x_1}{dt^2} + \frac{d^2 x_2}{dt^2} = 0$$

Since, the block m₁ is assumed to be moving downward (x₁ is increasing with time)

$$\therefore \qquad \frac{d^2 x_1}{dt^2} = + a_1$$

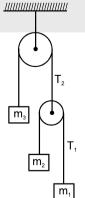
and block m₂ is assumed to be moving upward (x₂ is decreasing with time)

$$\therefore \quad \frac{d^2 x_2}{dt^2} = -a_2$$

Thus $a_1 - a_2 = 0$ or $a_1 = a_2 = a$ (say) is the required constraint relation. Substituting $a_1 = a_2 = a$ in equations (1) and (2) and solving them, we get

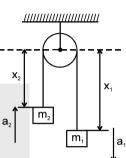
(i)
$$a = \left[\frac{m_1 - m_2}{m_1 + m_2}\right] g$$
 (ii) $T = \left[\frac{2m_1m_2}{m_1 + m_2}\right] g$

A system of three masses m₁, m₂ and m₃ are shown in the figure. The pulleys are smooth and Example 22. massless; the strings are massless and inextensible.

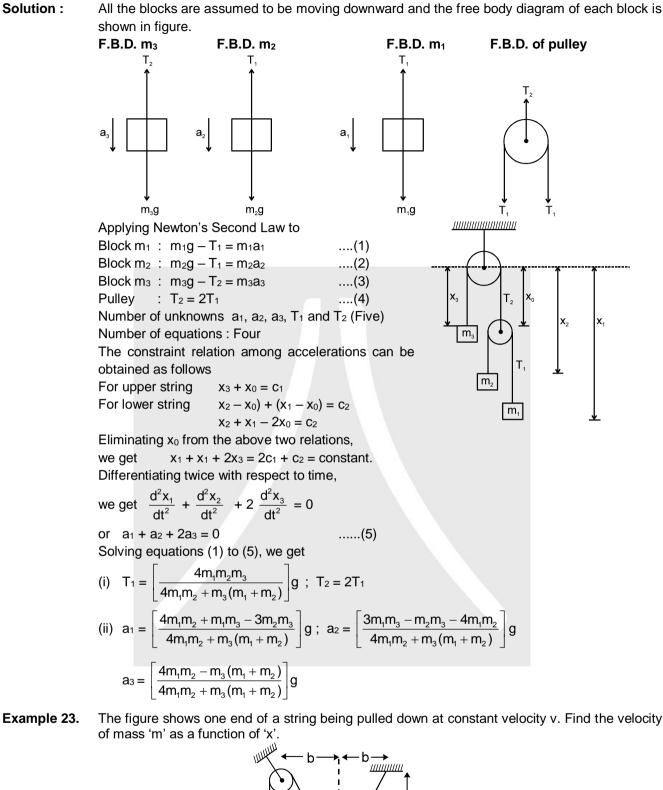


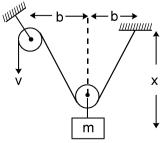
- (i) Find the tensions in the strings.
- (ii) Find the acceleration of each mass.





Position of each block is located w.r.t. centre of the pulley





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Solution : Using constraint equation $2\sqrt{x^2 + b^2} + y = \text{length of string} = \text{constant}$

Differentiating w.r.t. time : $\frac{2}{2\sqrt{x^2 + b^2}} \cdot 2x \left(\frac{dx}{dt}\right) + \left(\frac{dy}{dt}\right) = 0$ $\Rightarrow \left(\frac{dy}{dt}\right) = v \Rightarrow \left(\frac{dx}{dt}\right) = -\frac{v}{2x}\sqrt{x^2 + b^2}$

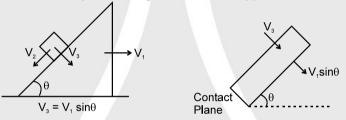
8.2 Wedge Constraint :

Conditions :

(i) There is a regular contact between two objects.

(ii) Objects are rigid.

The relative velocity perpendicular to the contact plane of the two rigid objects is always zero if there is a regular contact between the objects. Wedge constraint is applied for each contact.



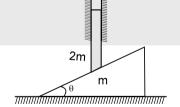
In other words,

Components of velocity along perpendicular direction to the contact plane of the two objects is always equal if there is no deformations and they remain in contact.

Solved Examples

Example 24.

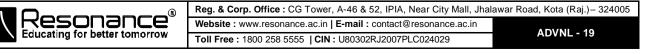
4. A rod of mass 2m moves vertically downward on the surface of wedge of mass as shown in figure. Find the relation between velocity of rod and that of the wedge at any instant.



Solution : Using wedge constraint. Component of velocity of rod along perpendicular to inclined surface is equal to velocity of wedge along that direction. $u \cos \theta = v \sin \theta$ $\frac{u}{v} = \tan \theta$

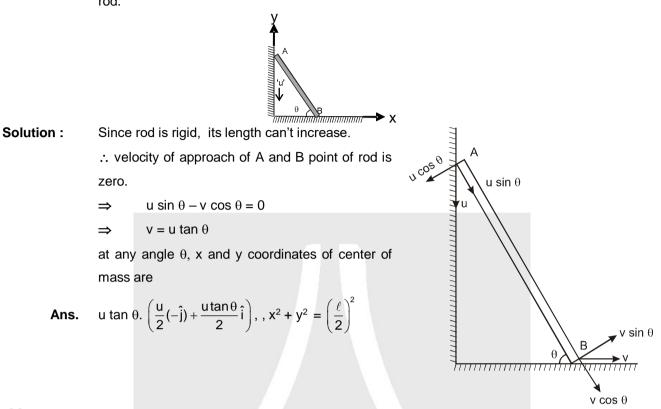
$$v = v \tan \theta$$

perpendicular to contact of two blocks



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Example 25. The velocity of end 'A' of rigid rod placed between two smooth vertical walls is 'u' along vertical direction. Find out the velocity of end 'B' of that rod, rod always remains in contact with the vertical wall and also find the velocity of centre of rod. also find equation of path of centre of rod.



9. NEWTON'S LAW FOR A SYSTEM

 $\vec{F}_{ext} = m_1 \vec{a}_1 + m_2 \vec{a}_2 + m_3 \vec{a}_3 + \dots$

 \vec{F}_{ext} = Net external force on the system.

m₁, m₂, m₃ are the masses of the objects of the system and $\vec{a}_1, \vec{a}_2, \vec{a}_3$ are the acceleration of the objects respectively.

Example 26. The block of mass m slides on a wedge of mass 'm' which is free to move on the horizontal ground. Find the accelerations of wedge and block. (All surfaces are smooth).

a \Rightarrow acceleration of wedge

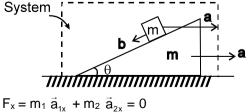
m m m

Solution :

Let.

b \Rightarrow acceleration of block with respect to wedge

Taking block and wedge as a system and applying Newton's law in the horizontal direction





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.....(1) $0 = ma + m(a - b \cos \theta)$ here 'a' and 'b' are two unknowns, so for making second equation, we draw F.B.D. of block. F.B.D of block.

using Newton's second law along inclined plane

mg sin θ = m (b – a cos θ)(2)

Now solving equations (1) and (2) we will get

$$a = \frac{mgsin\thetacos\theta}{m(1+sin^2\theta)} = \frac{gsin\thetacos\theta}{(1+sin^2\theta)} \text{ and } b = \frac{2gsin\theta}{(1+sin^2\theta)}$$

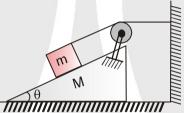
mg

So in vector form :

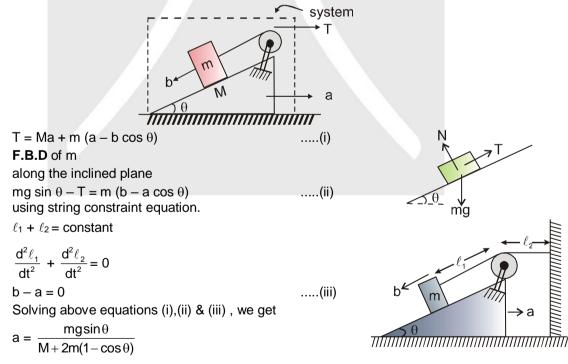
$$\vec{a}_{\text{wedge}} = a\hat{i} = \left(\frac{g\sin\theta\cos\theta}{1+\sin^2\theta}\right)\hat{i} \implies \vec{a}_{\text{block}} = (a-b\cos\theta)\hat{i} - b\sin\theta\hat{j}$$
$$\vec{a}_{\text{block}} = -\frac{g\sin\theta\cos\theta}{(1+\sin^2\theta)}\hat{i} - \frac{2g\sin^2\theta}{(1+\sin^2\theta)}\hat{j} \quad .$$

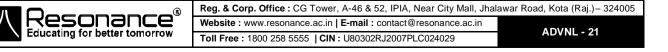
block =
$$-\frac{g\sin^2\theta\cos^2\theta}{(1+\sin^2\theta)}$$
 i $-\frac{2g\sin^2\theta}{(1+\sin^2\theta)}$ j

Example 27. For the arrangement shown in figure when the system is released, find the acceleration of wedge. Pulley and string are ideal and friction is absent.

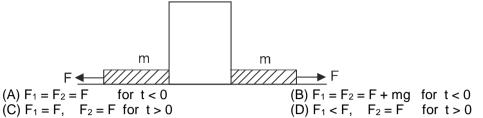


Solution : Considering block and wedge as a system and using. Newton's law for the system along x-direction



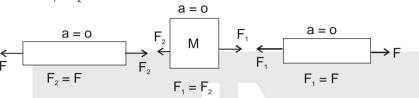


Example 28. A heavy block kept on a frictionless surface and being pulled by two ropes of equal mass m as shown in figure. At t = 0, the force on the left rope is withdrawn but the force on the right end continues to act. Let F_1 and F_2 be the magnitudes of the forces by the right rope and the left rope on the block respectively.



Solution :

For t < 0 As net force on system is zero, therefore acceleration of the system is zero \therefore F₁ = F₂ = F for t < 0



Ans. (A)

For t > 0 system is accelerated given by $a = \frac{r}{2 + M}$

$$\xrightarrow{}a \\ F_{1} \xleftarrow{} M \xrightarrow{} F$$

$$F - F_{1} = ma \\ F_{1} = F - ma \\ F_{1} = F - ma \\ F_{2} \xrightarrow{} M \xrightarrow{} F_{1}$$

$$F_{2} \xrightarrow{} M \xrightarrow{} F_{1}$$

$$F_{2} = Ma \\ F_{1} = F_{2} + Ma$$

$$F_{1} = F_{2} + Ma$$

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10. NEWTON'S LAW FOR NON INERTIAL FRAME :

 $\vec{F}_{\text{Real}} + \vec{F}_{\text{Pseudo}} = \vec{ma}$

Net sum of real and pseudo force is taken in the resultant force.

 \vec{a} = Acceleration of the particle in the non inertial frame

$\vec{F}_{Pseudo} = -m \vec{a}_{Frame}$

Pseudo force is always directed opposite to the direction of the acceleration of the frame. Pseudo force is an imaginary force and there is no action-reaction for it. So it has nothing to do with Newton's Third Law.

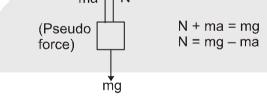
10.1 Reference Frame:

A frame of reference is basically a coordinate system in which motion of object is analyzed. There are two types of reference frames.

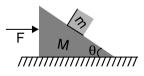
- (a) Inertial reference frame: Frame of reference either stationary or moving with constant velocity.
- (b) **Non-inertial reference frame:** A frame of reference moving with non-zero acceleration.

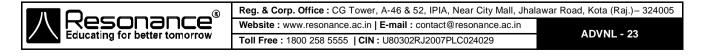


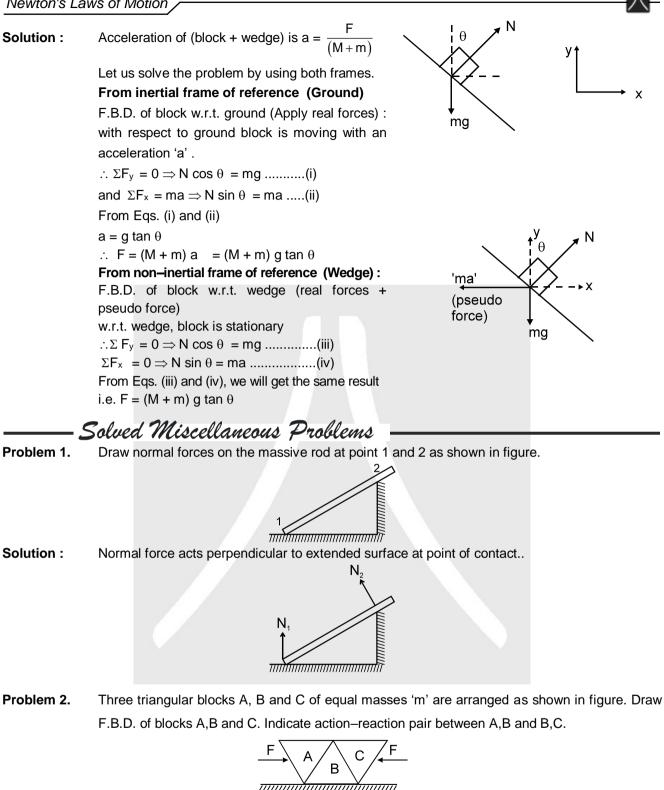
	Solved Examples ———
Example 29.	A lift having a simple pendulum attached with its ceiling is moving upward with constant acceleration 'a'. What will be the tension in the string of pendulum with respect to a boy inside the lift and a boy standing on earth, mass of bob of simple pendulum is m.
Solution :	F.B.D . of bob (with respect to ground) T - mg = ma T = mg + ma(i) With respect to boy inside the lift, the acceleration of bob is zero. So he will write above equation in this manner. $T - mg = m. (0)$ \therefore $T = mg$ He will tell the value of tension in string is mg. But this is 'wrong'. To correct his result, he makes a free body diagram in this manner, and uses Newton's second law. T = mg + ma(ii) By using this extra force , equations (i) and (ii) give the same result. This extra force is called pseudo force . This pseudo force is used when a problem is solved with a accelerating frame (Non-inertial) Note : Magnitude of Pseudo force = mass of system × acceleration of frame of reference. Direction of force: Opposite to the direction of acceleration of frame of reference, (not in the direction of motion of frame of reference)
Example 30. Solution :	A box is moving upward with retardation 'a' <g, "pseudo="" 'm'="" acting="" also="" and="" block="" block<="" box.="" by="" calculate="" direction="" exerted="" find="" force="" force"="" inside="" magnitude="" mass="" normal="" of="" on="" placed="" surface="" td="" the=""></g,>
Solution .	Pseudo force acts opposite to the direction of acceleration of \square \square \square reference frame. pseudo force = ma in upward direction F.B.D of 'm' w.r.t. box (non-inertial) \square \square \square \square \square \square \square \square \square \square

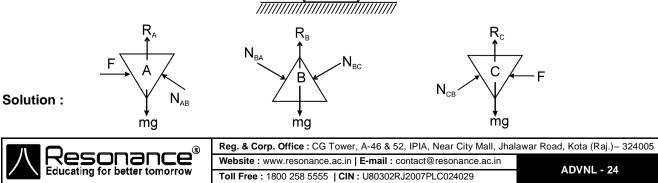


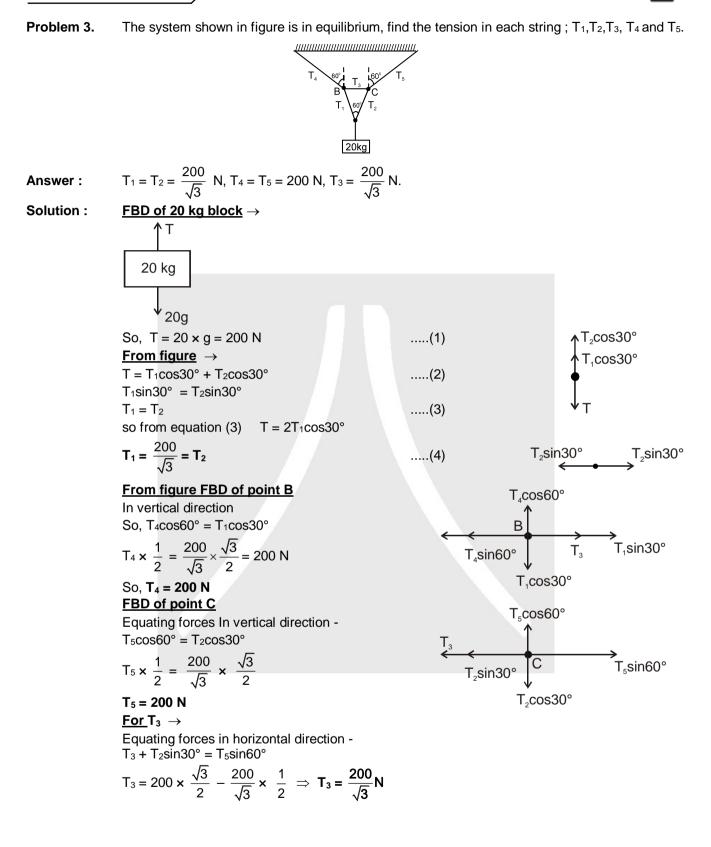
Example 31. All surfaces are smooth in the adjoining figure. Find F such that block remains stationary with respect to wedge.





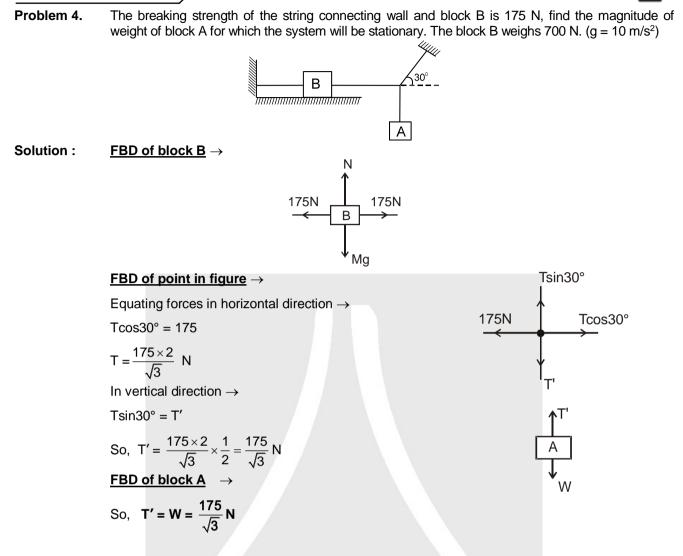




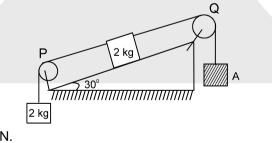




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Problem 5. In the arrangement shown in figure, what should be the mass of block A so that the system remains at rest. Also find force exerted by string on the pulley Q. ($g = 10 \text{ m/s}^2$)



m = 3 kg, $30\sqrt{3}$ N. Answer: From figure Solution :

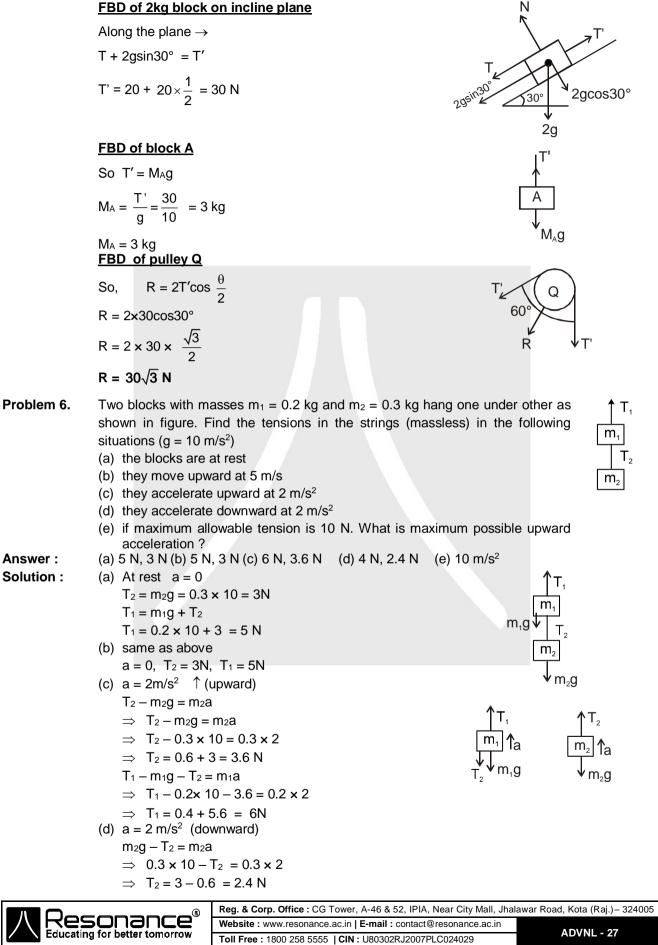
FBD of 2 kg block hanging vertically \rightarrow



 $T = 20 N \dots (1)$



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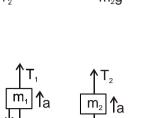


 $T_2 + m_1g - T_1 = m_1a$ \Rightarrow 2.4 + 2 - T₁ = 0.2 × 2 \Rightarrow T₁ = 4.4 - 0.4 = 4 N Ans. (e) Chance of breaking is of upper string means $T_1 < 10 N$ For m₁ – $T_1 - m_1 g - T_2 = m_1 a$ $10 - 2 - T_2 = 0.2 a$(1) For m₂ – $T_2 - m_2 g = m_2 a$ \Rightarrow T₂ - 3 = 0.3 a(2) Adding equation (1) and (2) $8 - 3 = 0.5 a \implies a = \frac{5}{0.5} = 10 \text{ m/s}^2$

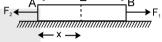
tension in rod at a distance x from end 'A',

 $T = F_2 - \frac{(F_2 - F_1)}{I} x$

Two forces F_1 and F_2 ($F_2 > F_1$) are applied at the free ends of uniform rod kept on a horizontal frictionless surface. Find







Answer:

Problem 7.

Solutio

Solution :
$$a = \frac{F_2 - F_1}{m}$$

$$T - F_1 = m_2 a$$

$$T - F_1 = \frac{m}{L} (L - x) \frac{F_2 - F_1}{m} (m_2 = \frac{m}{L} (L - x))$$

$$T = F_1 + \left(1 - \frac{x}{L}\right) (F_2 - F_1) = F_1 + F_2 - F_1 - \frac{x}{L} (F_2 - F_1) = F_2 - \frac{x}{L} (F_2 - F_1)$$
Problem 8. A 10 kg block kept on an inclined plane is pulled by a string applying 200 N force. A 10 N force is also applied on 10 kg

block as shown in figure.

- Find: (a) tension in the string.
 - (b) acceleration of 10 kg block.
 - (c) net force on pulley exerted by string
- (a) 200 N, (b) 14 m/s², (c) 200 $\sqrt{2}$ N Answer:
- Solution : (a) T = 200 N
 - (b) $T 10 mgsin\theta = ma$

$$\Rightarrow$$
 T - 10 - 50 = 10a

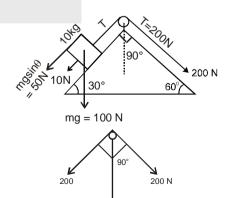
$$\Rightarrow 200 - 60 = 10a$$

$$\Rightarrow a = \frac{140}{10} = 14 \text{ m/s}^2$$

(c)
$$(F_R) = \sqrt{(200)^2 + (200)^2}$$

= 200 $\sqrt{2}$ N Ans.

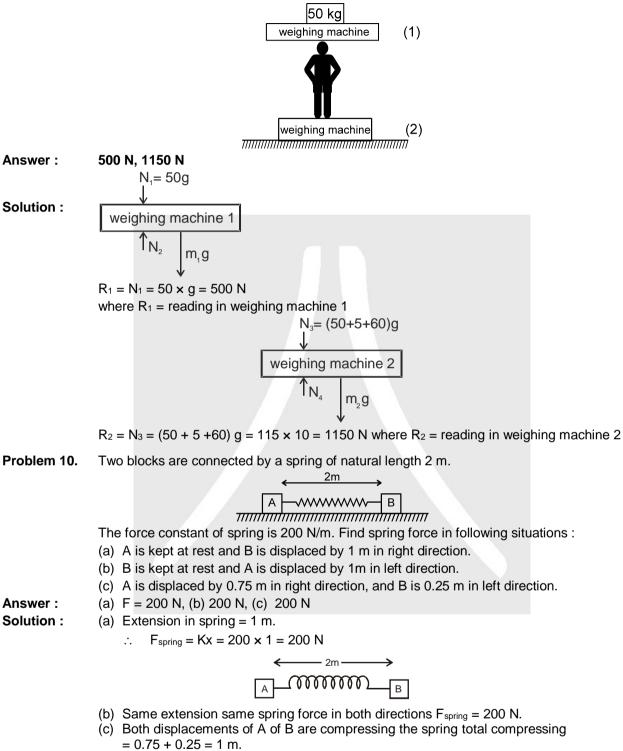
200 N



(**F**_R)



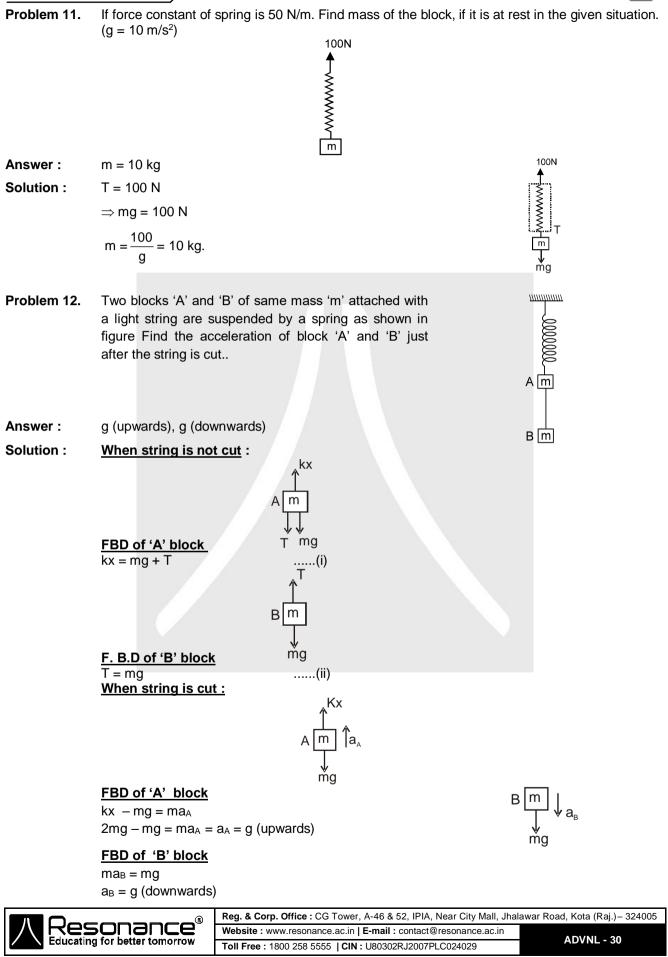
Problem 9. A man of mass 60 kg is standing on a weighing machine (2) of mass 5kg placed on ground. Another similar weighing machine is placed over man's head. A block of mass 50kg is put on the weighing machine (1). Calculate the readings of weighing machines (1) and (2) (g = 10 m/s²)



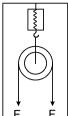
:. $F_{spring} = kx = 200 \times 1 = 200 N.$



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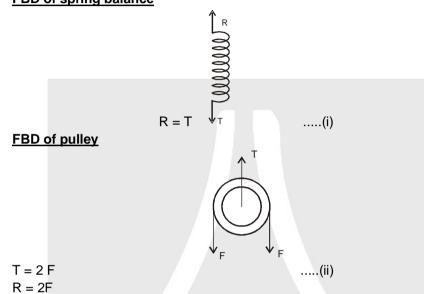


Problem 13. Find the reading of spring balance in the adjoining figure, pulley and strings are ideal.

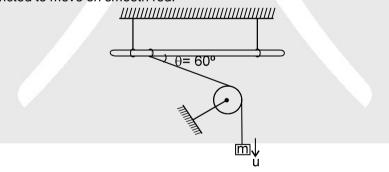


Answer: 2F

Solution : FBD of spring balance



Problem 14. The figure shows mass m moves with velocity u. Find the velocity of ring at that moment. Ring is restricted to move on smooth rod.



Answer :

$$V_R = \frac{u}{\cos\theta}, \qquad V_R = 2u$$

Velocity along string remains same .

Solution :

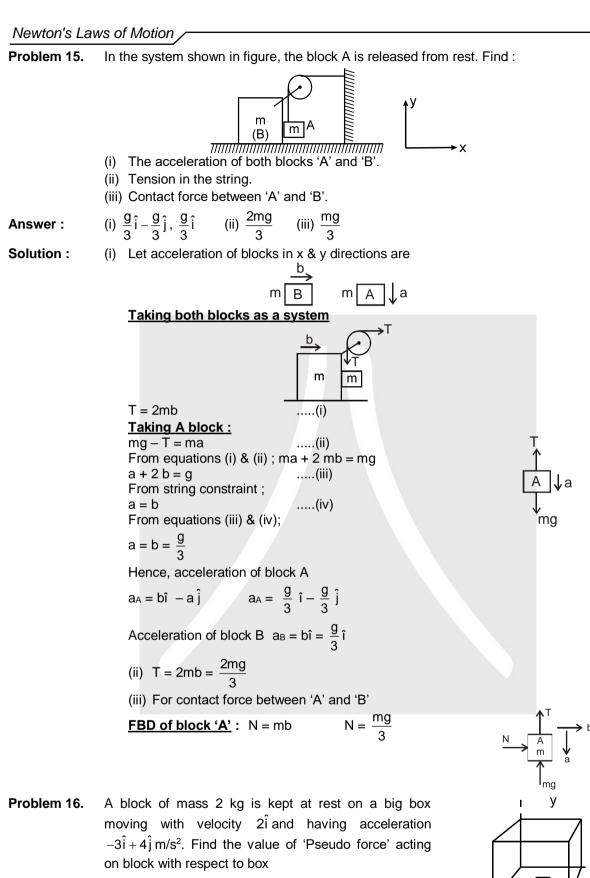
$$V_{R} \cos\theta = u$$
$$V_{R} = \frac{u}{\cos\theta}$$
$$\theta = 60^{\circ}$$
$$V_{R} = 2u$$



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Answer :

$$\vec{F}_{pseudo} = -m\vec{a}_{frame} = -2(-3\hat{i} + 4\hat{j})$$
$$F = 6\hat{i} - 8\hat{j} .$$



ъX



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